



CHRIST THE KING ENGINEERING COLLEGE

Karamadai, Coimbatore - 641 104
Approved by AICTE, New Delhi & Affiliated to Anna University, Chennai



B.E. - COMPUTER SCIENCE AND ENGINEERING

SIXTH SEMESTER

CIA-1

SET B

Answer key

1. 1. Nonblocking primitive 2. Blocking primitive 3. Asynchronous primitive 4. Synchronous primitive
2. An *asynchronous execution* is an execution in which
There is no processor synchrony and there is no bound on the drift rate of processor clocks,
Message delays (transmission + propagation times) are finite but unbounded, and
There is no upper bound on the time taken by a process to execute a step.
A *synchronous execution* is an execution in which
(i) processors are synchronized and the clock drift rate between any two processors is bounded,
(ii) message delivery (transmission + delivery) times are such that they occur in one logical step or round, and
(iii) there is a known upper bound on the time taken by a process to execute a step.
3. a) Functional distribution b) Load distribution/balancing c) Replication of processing power d) Physical separation e) Economics
4. The order of delivery of messages in a distributed system is an important aspect of system executions because it determines the messaging behaviour that can be expected by the distributed program.
5. (i) non-FIFO, (ii) FIFO, (iii) causal order (iv) synchronous order.
6. A. Even if the state of all the components is not recorded at the same instant, such a state will be meaningful provided every message that is recorded as received is also recorded as sent. Basic idea is that a state should not violate causality—
effects should not be present without their cause. A message cannot be received until it was sent.



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A Lamport logical clock is a monotonically increasing software counter, whose value need bear no particular relationship to any physical clock. Each process p_i keeps its own logical clock, L_i , which it uses to apply so-called *Lamport timestamps* to events. We denote the timestamp of event e at p_i by $L_i(e)$, and by $L(e)$ we denote the timestamp of event e at whatever process it occurred at.

7. A. When referring to a message without regard for the identity of the sender and receiver processes, we use m^i . For message m^i , its send and receive events are denoted as s^i and r^i , respectively. More generally, send and receive events are denoted simply as s and r . When the relationship between the message and its send and receive events is to be stressed, we also use M , $\text{send}(M)$, and $\text{receive}(M)$ respectively.

Several orderings on messages have been defined

- (i) non-FIFO, (ii) FIFO, (iii) causal order (iv) synchronous order.

b.

8. a. **Challenges:** 1. Heterogeneity 2. Openness 3. Security 4. Scalability
5. Failure handling 6. Concurrency 7. Transparency 8. Quality of service
Design issues: 1. Openness 2. Resource Sharing 3. Concurrency
4. Scalability 5. Fault-Tolerance 6. Transparency 7. High-Performance

b. **Parallel system:** 1. process the data simultaneously, and increase the computational speed of a computer system. 2. Tasks are performed with a more speedy process. 3. It is also known as a tightly coupled system 4. These systems share a memory, clock, and peripheral devices 5. In this, all processors share a single master clock for synchronization.

Distributed system : 1. applications are running on multiple computers linked by communication lines. 2. consists of a number of computers that are connected and managed so that they share the job processing load among various computers distributed over the network 3. each processor has its own memory. 4. also known as loosely coupled systems. 4. These systems do not share memory or clock in contrast to parallel systems. 5. In this there is no global clock in distributed computing, it uses various synchronization algorithms.



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